

# imajbox<sup>®</sup>

## MOBILE MAPPING SYSTEM

Mounted on cars, trucks or trains, imajbox<sup>®</sup> can survey from a few to thousands of kilometers.

Punctual, recurrent or nationwide projects, imajbox<sup>®</sup> is the perfect tool to survey a network, thus having up-to-date data.



### ACCURATE

Proprietary algorithms to process sensors' raw data for the continuous and accurate spatial positioning.



### SIMPLE

Independent, all-in-one, standalone and autocalibrated. No wiring required.



### PRODUCTIVE

High speed survey for a large scale data collection.



### CONNECTED

Controlled by WiFi and connectors for external sensors integration.

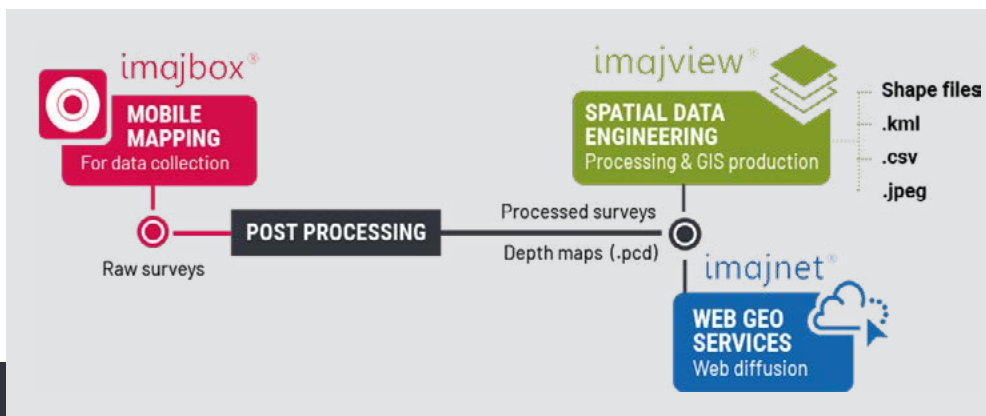


### FLEXIBLE

Easily mounted in every orientations with the tripod's suction pads.

### A RESPONSE TO MANY ISSUES:

- GIS and mapping
- Engineering studies
- Linear Referencing System
- Maintenance management
- Work control
- Planning and budgeting
- Monitoring
- Asset inventory



#### IMAJING SAS

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# INERTIAL MOVEMENT UNIT (IMU)

## DX3

### Gyroscopes:

Dynamic range:  $\pm 280^\circ/s$   
 In-run bias stability:  $12^\circ/hr$   
 Angular random walk:  $0.56/\sqrt{hr}$

### Accelerometers:

Dynamic range:  $\pm 5g$   
 In-run bias stability:  $0,25mg$   
 Velocity random walk:  $0.073m/sec/\sqrt{hr}$

## DX4

### Gyroscopes:

Dynamic range:  $\pm 480^\circ/s$   
 In-run bias stability:  $6.25^\circ/hr$   
 Angular random walk:  $0.3/\sqrt{hr}$

### Accelerometers:

Dynamic range:  $\pm 18g$   
 In-run bias stability:  $0,1mg$   
 Velocity random walk:  $0.029m/sec/\sqrt{hr}$

## PACKAGE

- 1 unit delivered in a small fly case
- 3 suction pads
- 1 USB Pendrive 128GB
- 1 external patch antenna (L1/L2)
- Security strap
- Cigarette lighter power supply cable
- AC/DC converter 110/240V 12V 3A



SPECIFICATIONS	3S	3SX+	3TX+
<b>Image sensor</b> Single CMOS Global Shutter 8,9MP	●	●	●
<b>Resolution</b> 4096 x 2160 pixels	●	●	● <i>(Cropped for high speed: 2200 x 2160)</i>
<b>HFOV</b> 100°	●	●	●
<b>Maximum frame rate</b>	10 fps	10 fps	17 fps <i>(high speed mode)</i>
<b>IMU</b> 6 axis (details on the left)	DX3	DX4	DX4
<b>Real time GNSS (NTRIP corrections)</b>			
Standalone	●	●	●
SBAS			●
DGNSS		●	●
PPP			●
RTK		●	●
<b>Post Processed GNSS (RINEX corrections)</b>			
Standalone	●		●
SBAS	●		●
DGNSS	●		●
PPK			●
<b>GNSS tracked frequencies</b>			
GPS	L1	L1, L2	L1, L2, L5
GLONASS	L1	L1, L2	L1, L2, L3
Galileo	E1	E1, E5	E1, E5a, E5b, AltBoc
BeiDou		B1, B2	B1, B2
SBAS			EGNOS, WAAS, GAGAN, MSAS, SDCM (L1, L5)
QZSS			L1, L2, L5
L-Band (Terrastar)			●
<b>Final extracted data absolute accuracy</b>			
X, Y	< 0,5m DRMS <i>(with DGNSS)</i>	< 0,1m CEP <i>(with RTK)</i>	< 0,1m DRMS <i>(with PPK)</i>
Z	< 2m	< 0,2m	< 0,1m
<b>Internal SSD (512 GB optional)</b>	128GB	128GB	128GB
<b>Application</b>	Road	Road	Road / Rail
<b>Maximum speed</b>	180 km / h	180 km / h	306 km / h
<b>Connectivity</b>			
USB 3 / Ethernet / Wi-Fi host <i>(for web remote control)</i>	●	●	●
Wi-Fi client (for corrections)		●	●

## HARDWARE

**Operational limits:** -10°C to +40°C  
**Protection level:** IP 65  
**Dimensions:** 175 x 165 x 145  
**Weight:** 2 kgs  
**Internal battery:** 3h  
**Power supply:** 12 V / A

## SOFTWARE

**imajbox® is delivered with Post processing software for Windows X64:**  
 imajing browser  
 imajing 3D Pro  
 imajing tight hybrid algorithms *(only for 3S)*  
 imajing InertialVision fusion algorithms *(only for 3SX+ and 3TX+)*  
 Kinematic post processing module *(only for 3TX+)*

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