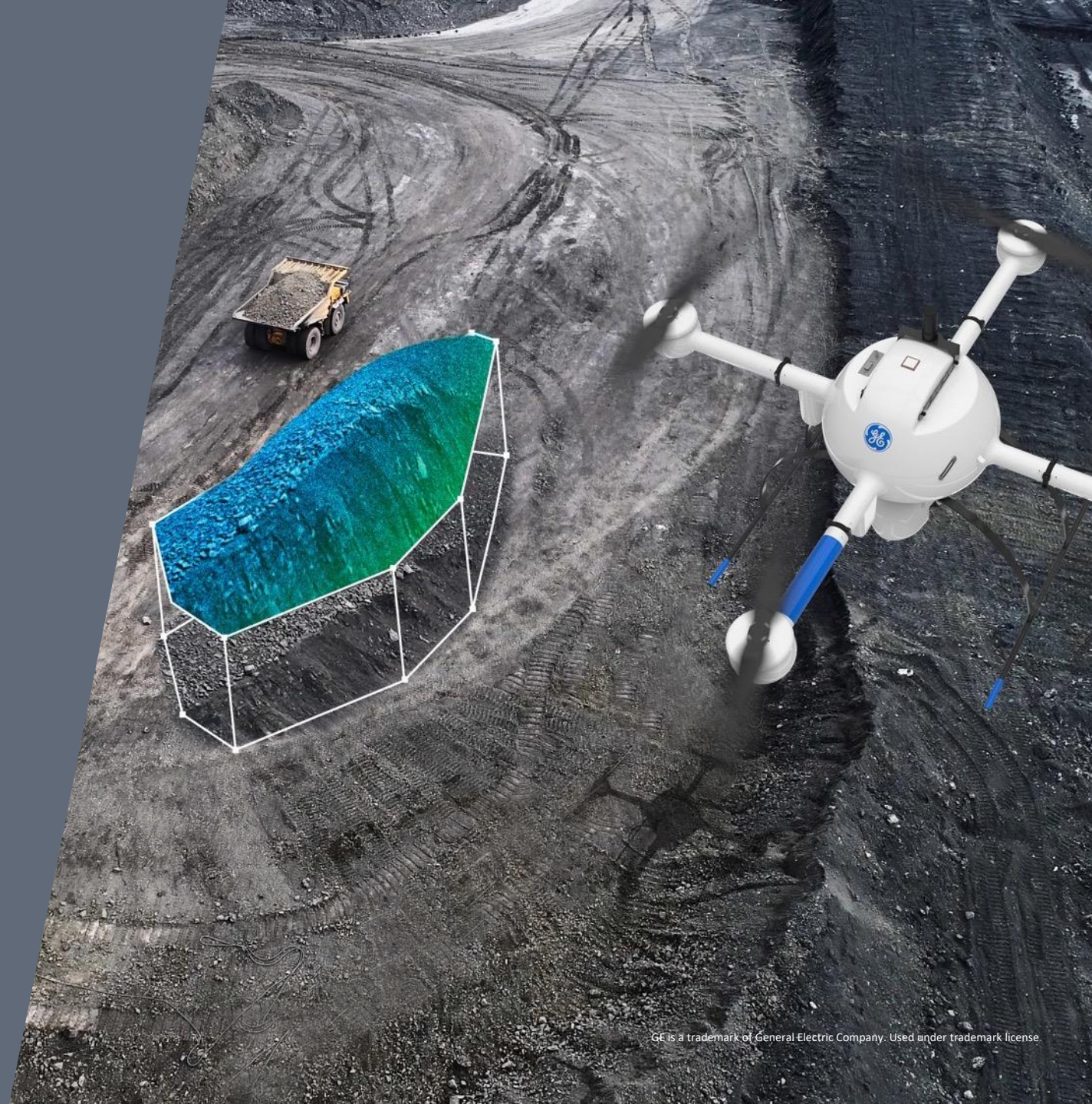




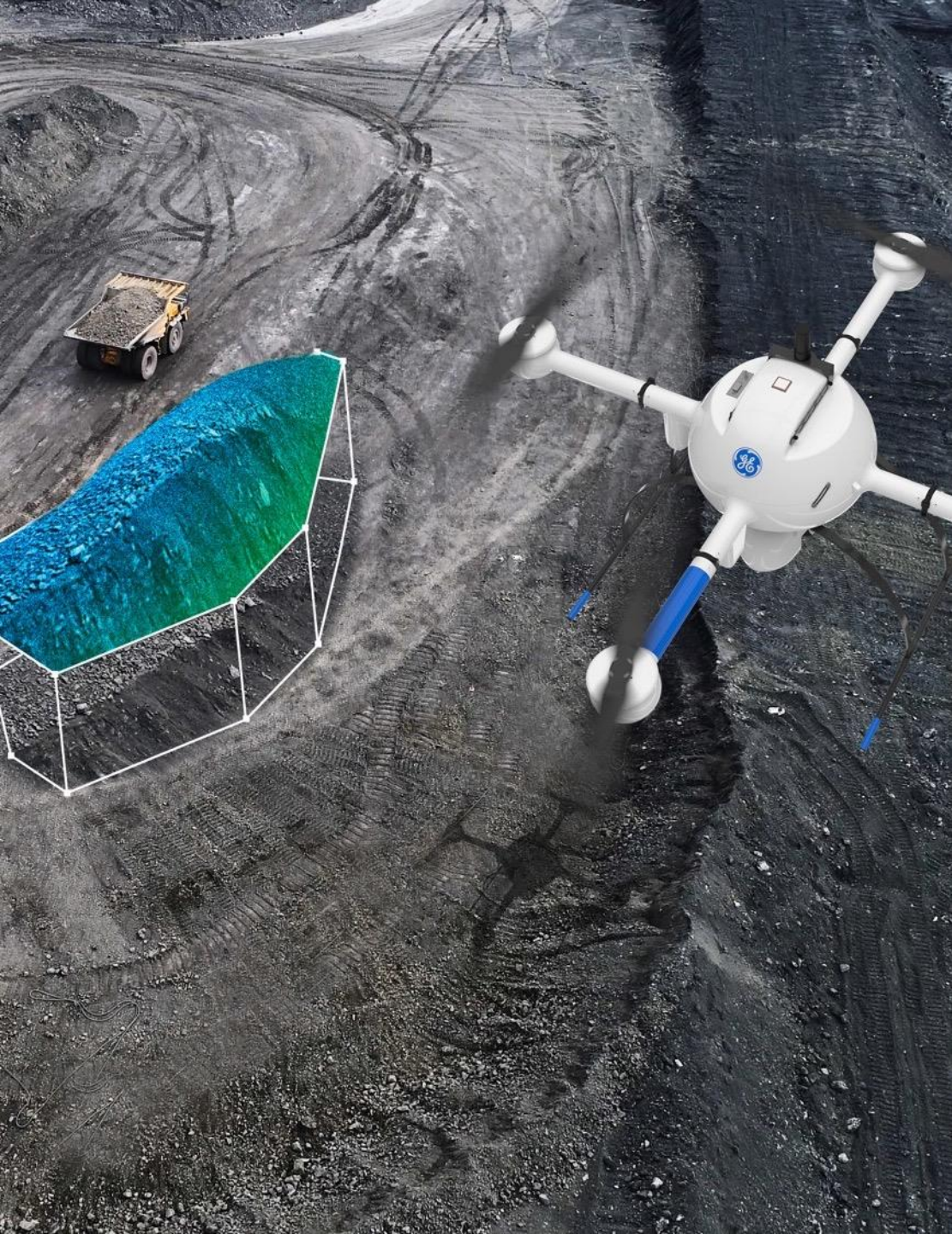
PUTTING MICRODRONES TO WORK FOR YOU.

General Presentation

Updated June 2021



GE is a trademark of General Electric Company. Used under trademark license.

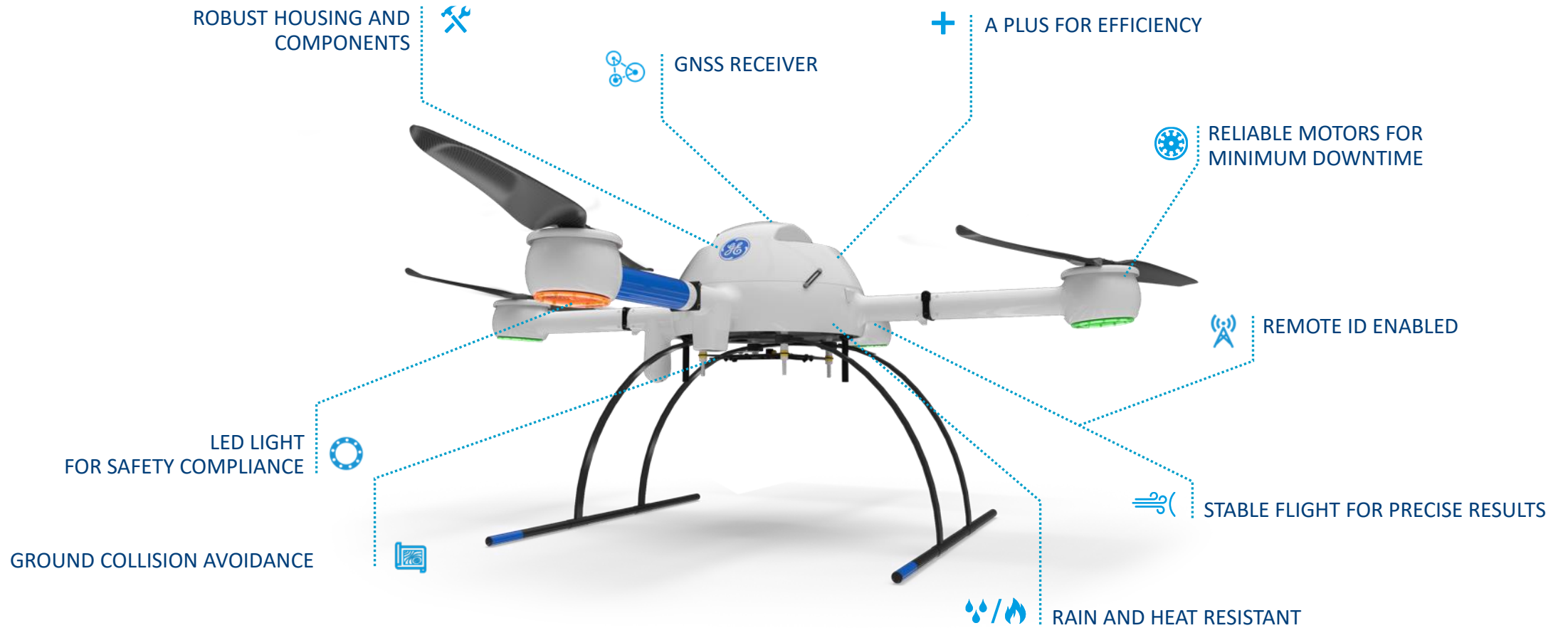


TWO INDUSTRY EXPERTS. ONE SIMPLE CHOICE.

Microdrones® and GE, have joined forces to offer you a full line of workhorse industrial equipment.

All systems are fully integrated and include the aircraft, sensors, workflow, service and support to help you work smarter.

BENEFITS OF THE MICRODRONES AIRCRAFT





mdLiDAR
1000LR

GE industrial drone line

LONGER RANGE LIDAR & 26MP CAMERA ALL IN ONE, TO COVER MORE GROUND

mdLiDAR1000LR means longer range. You'll cover more ground from above. This translates to more efficiency than ever - the survey equipment, software, workflow, training and support that you need to be productive in the field.





SURVEY GRADE DRONE LASER SCANNING

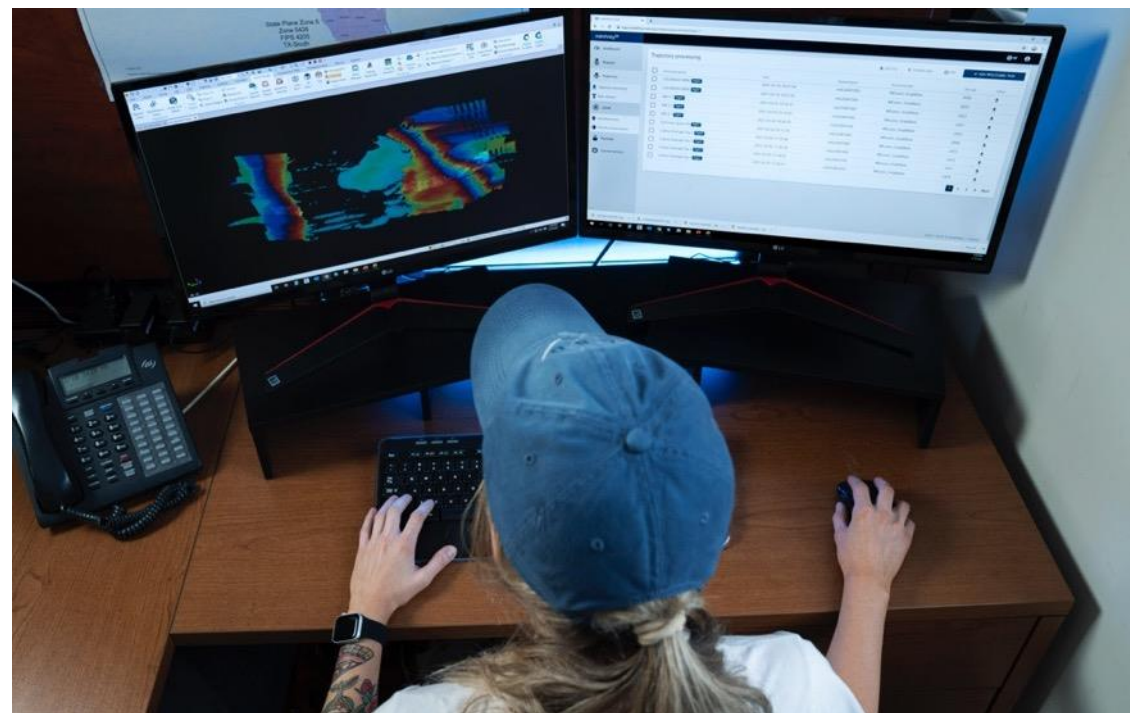
By combining our robust and field proven md4-1000 airframe, with a fully integrated high-resolution LiDAR & camera payload, you can capture ultra dense LiDAR data quickly and safely in the field, and then turn it into a 3D point cloud back at the office or on your laptop.



LiDAR + mdaaS + EASY TO USE mdInfinity SOFTWARE = EXTREME GEOSPATIAL PRODUCTIVITY, NOW IN HIGH RESOLUTION

Microdrones has developed an end-to-end LiDAR solution combining a drone, a LiDAR payload, a fully integrated LiDAR processing and photogrammetry software workflow, and world class support to consistently provide quality deliverables.

mdLiDAR1000LR is a fully integrated system for producing 3D point clouds optimized for land surveying, construction, oil & gas and mining applications.





WHY SHOULD YOU INVEST IN DRONE BASED LiDAR?

The mdLiDAR1000LR can help streamline your current workflow to become more efficient, while helping you to complete more projects.

EASY END-TO-END WORKFLOW:



PLAN FLY PROCESS VISUALIZE



- Simple mission planning using mdCockpit
- User selects flying height, drone speed and LiDAR strip overlap



- Fully automated mission execution, realtime monitoring, and flight control using mdCockpit



- Thorough georeferencing data processing using the Applanix APX-15 UAV DG and mdInfinity Software
- Automated final point cloud processing using mdInfinity processing software

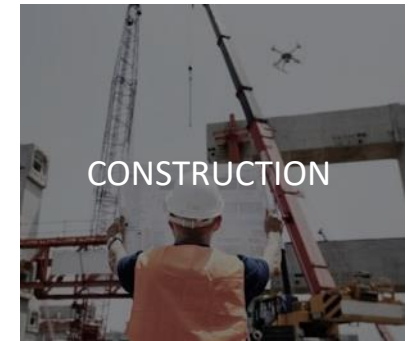


- Final point cloud in standard ASPRS LAS format, View your deliverable in mdInfinity software, or export to use within any GIS or CAD software environment that you currently use



WHAT CAN YOU DO WITH IT?

mdLiDAR1000LR is a versatile package that can be used for a wide range of applications. Some of the most common uses are:



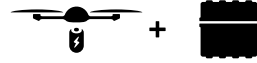
SURVEY EQUIPMENT



PLATFORM



md4-1000



Charger, Flight Battery
& Rugged Carrying
Case



Integrated Cooling
Covers



Mag-less
Navigation



LED Light Rings

COMMUNICATIONS



Encrypted Digital
Data Link



mdRC



Extended
Communication Range
Operation



Multiple Tablet
Control



Remote ID Enabled

SURVEY EQUIPMENT



PAYLOAD



Fully Integrated High Resolution LiDAR & Camera



Applanix APX-15 UAV DG



SURVEY EQUIPMENT SOFTWARE



mdCockpit Tablet Software



Tap & Fly



mdInfinity^{GO}

mdaaS

DG ENABLED



mdINFINITY IS A POWERFUL ECOSYSTEM THAT WILL ENABLE YOU TO QUICKLY AND EFFICIENTLY PROCESS GEOSPATIAL DATA, WITH CONVENIENT PAYMENT OPTIONS.

Available Data Processing Modules:

- [Trajectory processing](#)
- [Georeferencing](#)
- [Boresight calibration](#)
- [Strip adjustment](#)
- [Precision enhancement](#)
- [Point Cloud Direct Colorization](#)
- [FORMap](#)



mdInfinity is available in online and desktop versions.

SOLUTION COMPONENTS

Platform

md4-1000

Payload

- LiDAR Sensor: Velodyne PUCK VLP-32
- Camera Sensor: Microdrones CMOS APS-C 26MP (23.5mmx15.6mm)
- Georeferencing: APX-15 UAV

Software

- mdCockpit
- mdInfinity

TECHNICAL SPECIFICATIONS

Takeoff Weight (TOW)

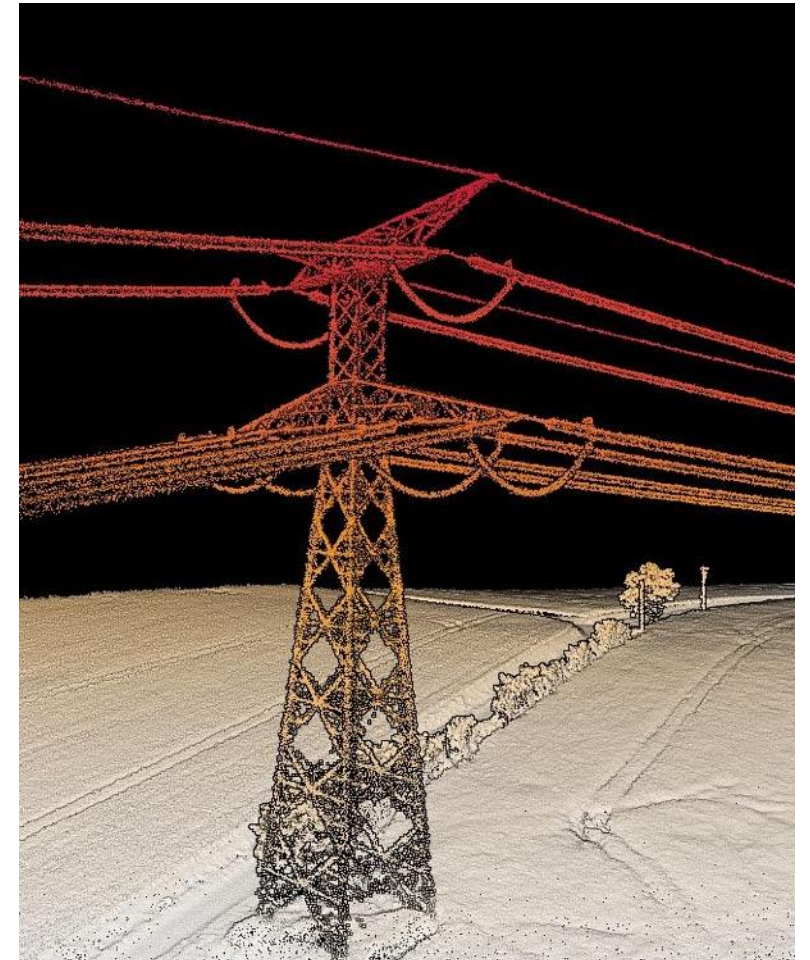
6400 g

System Operational Temperature

-10 °C to 40 °C
14 °F to 104 °F

System Accuracy

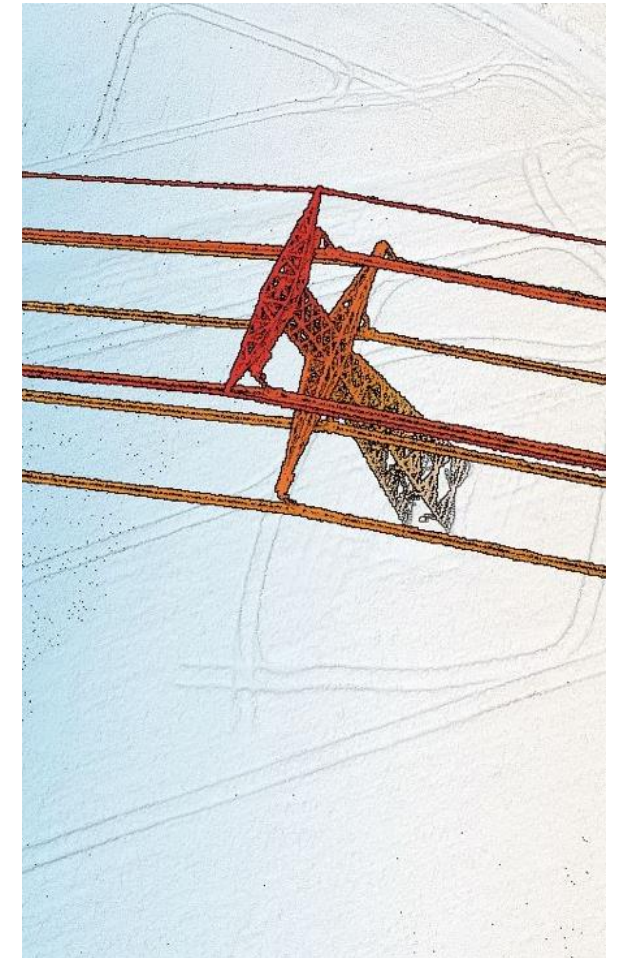
- LiDAR Point Cloud:
 - 4 cm RMSE
- Photogrammetry:
 - Horizontal: 2-3 pixels
 - Vertical: 3-5 pixels



TECHNICAL SPECS



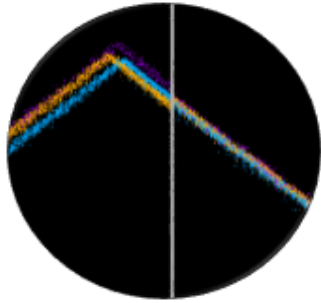
Flight Altitude AGL ^(1,2) (ft/m)	200/60	300/90	400/120
Speed (m/s)	Covered square area at 30% sidelap (ac/ha)		
4	94/38	116/47	126/51
6	128/52	155/63	222/90
8	158/64	235/95	297/120
Speed (m/s)	Average Point Density in pts/m ^{2(2,3)} (square area/1 scan line)		
4	313/368	208/245	156/184
6	208/245	139/163	104/123
8	156/184	104/123	78/92
Camera GSD (mm)	9	13.5	18
Number of Laser Returns	2	2	2
Swath Width (ft/m)	400/120	600/180	800/240
Flight Time (minutes)⁽²⁾	Up to 35 minutes, typically 25 minutes		
System Operating Temperature	-10°C (14°F) up to 40°C (104°F)		



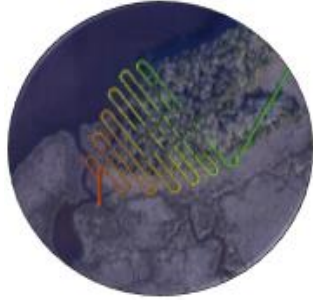
⁽¹⁾ Flight Altitude Above Ground Level (AGL)

⁽²⁾ Coverage estimated for approximately 25 minutes of flight time

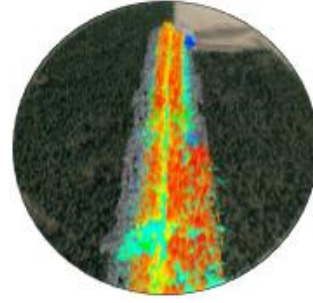
⁽³⁾ Average density calculated with 30% overlap on 5 lines, average density will depend on surface type.



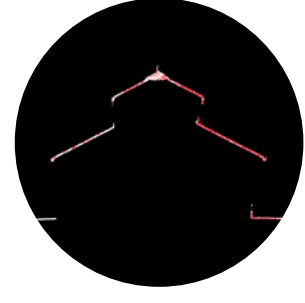
BORESIGHT CALIBRATION



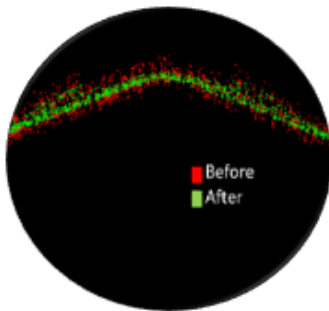
TRAJECTORY PROCESSING



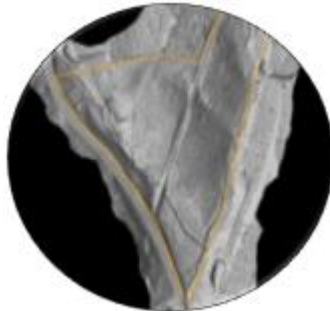
GEOREFERENCING



STRIP ADJUSTMENT



PRECISION ENHANCEMENT



GROUND CLASSIFICATION



POINT CLOUD COLORIZATION



FORMap

TRAJECTORY PROCESSING

Improve the accuracy of the position and attitude of sensor collected during the flight.

The Trajectory Processing module is a user friendly workflow for users to process raw GNSS data (with or without base station), hybridize IMU and GNSS data to produce a smooth trajectory file and export it as a EO/sbet files in the desired coordinate system.

Users can validate the trajectory parameters before processing and obtain different types of EO files depending on the software they will use afterwards.



INTRO VIDEO



BENIFITS VIDEO

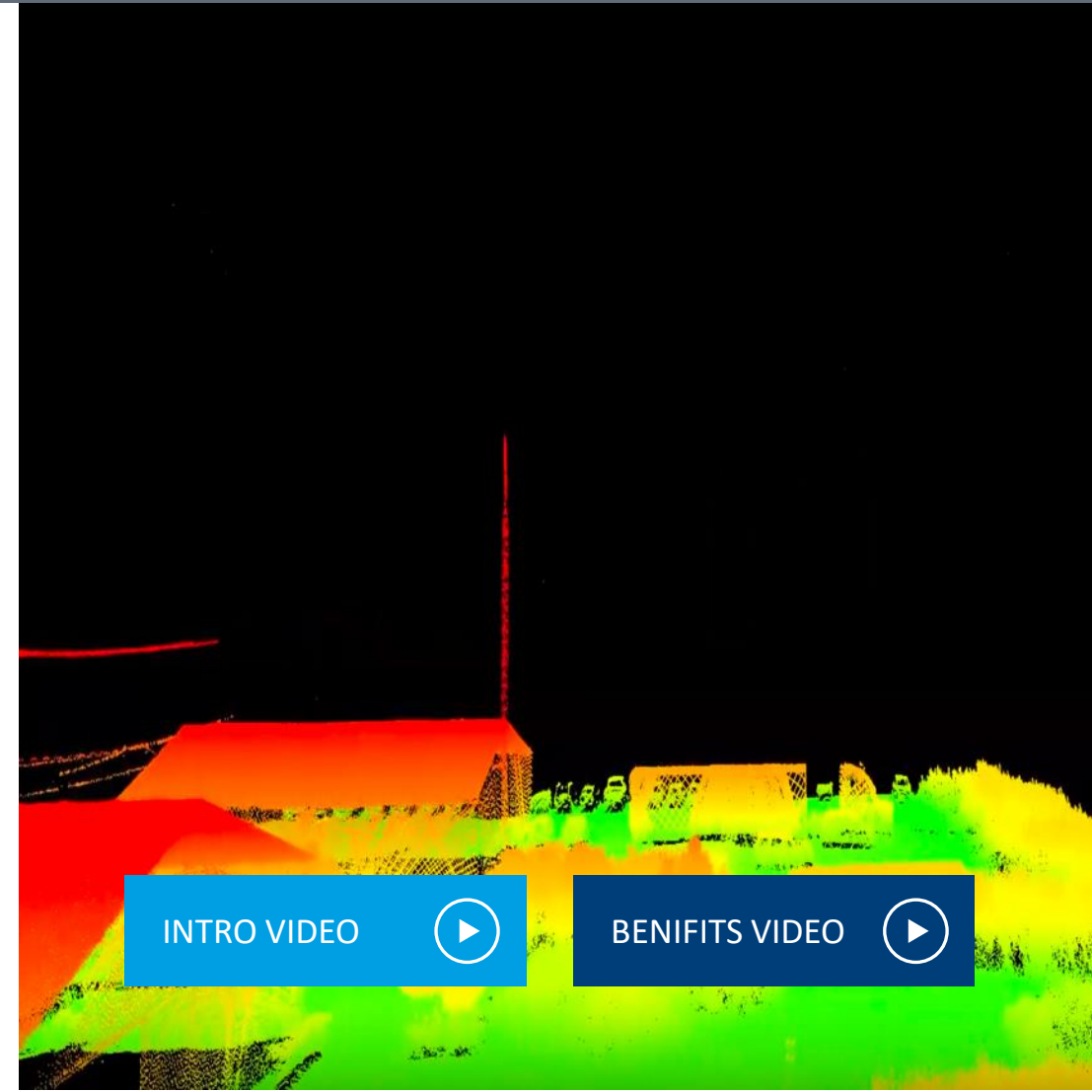


GEOREFERENCING

Anchor geographic coordinates to every point of your pointcloud.

Georeferencing transforms the raw data from the LiDAR (range and bearing angles), the GNSS and IMU (orientation and positioning) to 3D point cloud and associated data.

With the specifications of the raw data, Microdrones produces a georeferenced point cloud in geographic coordinates without any geodetic distortion, or in a local mapping frame specified by the user.



BORESIGHT CALIBRATION

Correct boresight misalignment of your specific product.

Calibration tackles the issue of the alignment of the LiDAR and the IMU body frames.

While a data set may seem clear at high-scale, LiDAR to IMU boresight angles may produce some inconsistency in the data set.

With the Microdrones LIBAC (LiDAR -IMU Boresight Automatic Calibration) tool, the misalignment is computed automatically and boresight angles can be applied to georeference the data set without any boresight bias.



INTRO VIDEO



BENIFITS VIDEO

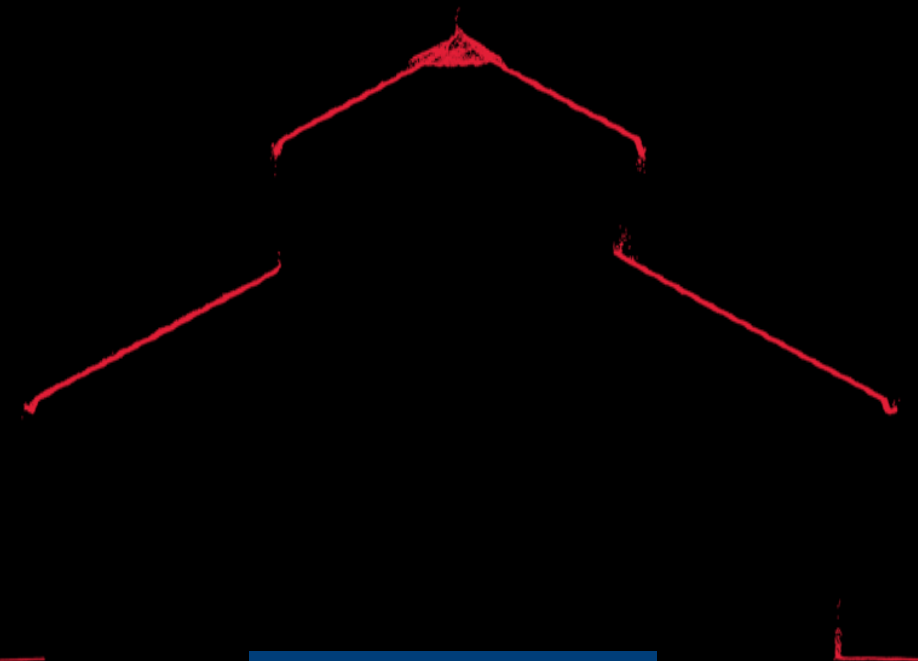


STRIP ADJUSTMENT

Reinforce the consistency between LiDAR survey strips.

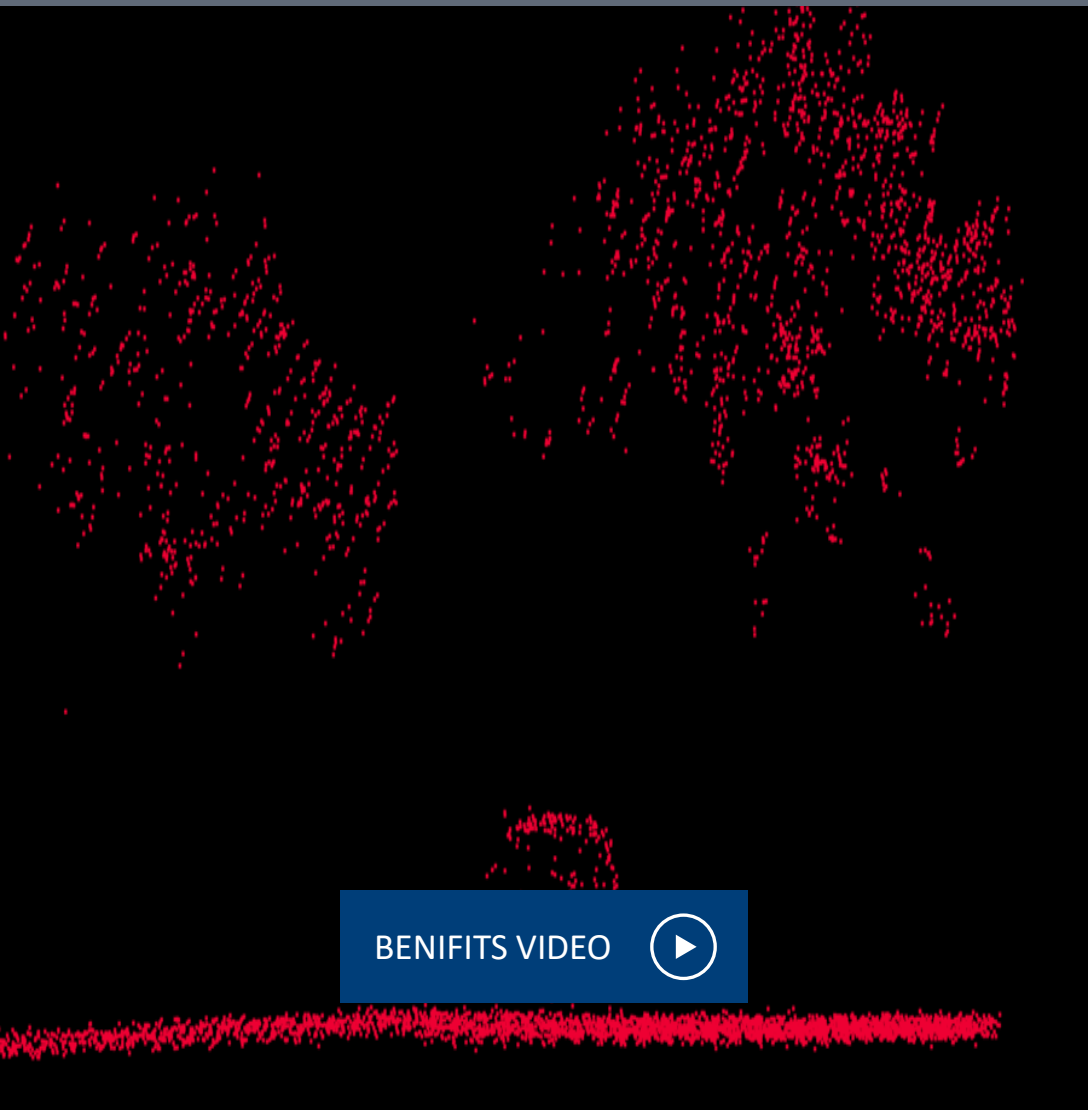
The Microdrones strip adjustment method offers numerous options to improve the consistency between lines. Using an advanced optimization engine and a smart tie point selector, position and angles of the drone are adjusted through time in order to get a perfect matching of the data.

A separate module enables the user to achieve the absolute point cloud registration to GCP, as defined by the user.



BENIFITS VIDEO





BENIFITS VIDEO



PRECISION ENHANCEMENT

Remove outliers and reduce the noise level of your point clouds.

Precision enhancement solves the problem of outlier rejection and denoising in a unified environment.

Microdrones outlier rejection is based on density and morphology which enable the user to isolate points belonging to relevant structures. (e.g. poles, cables) The Microdrones denoising module reduces the noise level while preserving edges and irregular features in the point cloud.

POINT CLOUD DIRECT COLORIZATION

Colorize a point cloud without referring to a full photogrammetric process by managing occlusions.

Microdrones point cloud colorization is done after the LiDAR point cloud generation, without the need of a full prior photogrammetric process.

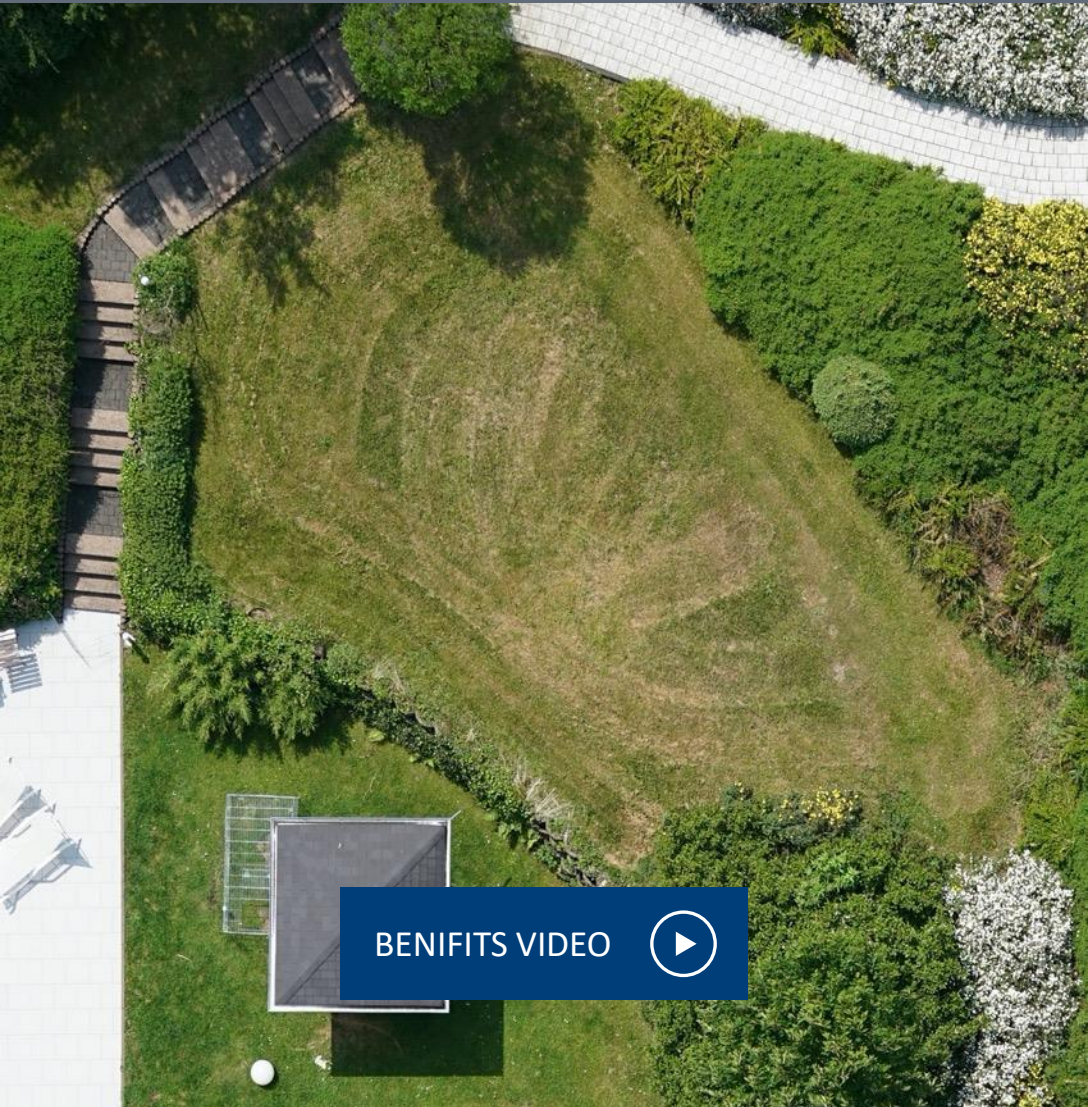
Occlusions in the point cloud are colorized by considering only the relevant part of the point cloud.

Only available through mdInfinity Custom Services



BENIFITS VIDEO





FORMap

Generate an orthomosaic and dense point cloud from photogrammetric survey data.

FORMap implements a rapid and comprehensive photogrammetric workflow to transform images and navigation data in an orthomosaic and a dense point cloud. The main feature of FORMap is a fast response time (2-4 sec/image) to produce results in a few minutes after drone landing.

Orthomosaic produced by FORMap are geometrically consistent and without distortion.

Only available through [mdInfinity Custom Services](#)

NEXT STEPS

